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Physics-informed Graph Neural Network for prediciting Power Generation of Wave Farms

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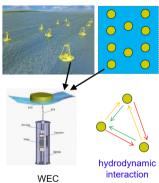
Outline

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 Wave Energy Converters
 Surrogate Modelling
 Hydrodynamic Coefficients
- ► Graph Neural Networks
 Introduction to Graph
 GNN: Fundamentals
 Invariant GNN with Random Node Features
- ► Implementation Details
- ► Results
- ► Conclusion

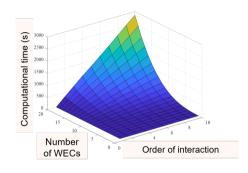




Wave Energy Converters (WECs)



- WECs (buoys) are often deployed in arrays called wave farms
- Depending on layout, different performance, e.g. power

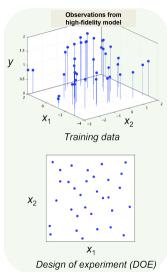


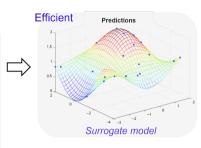
- For high fidelity models and larger arrays, predicting power for different layout is expensive
- Parametric study, design optimization, uncertainty quantification become impossible
- Surrogate Model preferred

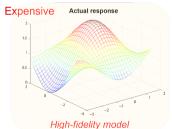
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Surrogate Modelling







- Polynomial Response Surfaces
- Gaussian Process(GP)
 Model
- Artificial Neural Networks
 (ANN)



Approximation

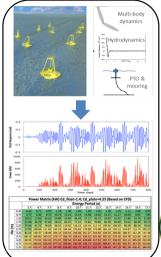






Hydrodynamic Coefficients

- *Li et. al. 2023* used PGP to predict hydrodynamic coefficients on wave farms and achieved good results
- Hydrodynamic Coefficients
 - Added Mass (am): real, $n_{wec} \times n_{wec}$
 - Added Damping (ad): real, $n_{wec} \times n_{wec}$
 - Wave Excitation Force (F): complex, n_{wec}
- Added mass and added damping: effects of radiated waves from WECs
- Wave Excitation Force: effect of incident and diffracted waves
- Power difficult to model, hence work on coefficients

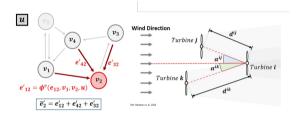






Graph Neural Network (GNN)

Good result on Wind Farm, analogous to Wave Farm



GNN on wind farm (Bentsen 2022)

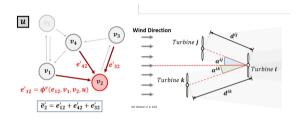


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Graph Neural Network (GNN)

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GNN on wind farm (Bentsen 2022)

Advantages of GNN:

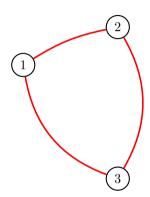
- Scalability: easy to scale for larger arrays
- Performance: captures intricate relationship with high accuracy
- Efficiency: can operate in parallel



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What is Graph?



A simple Graph

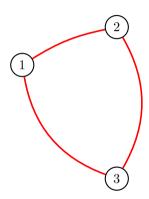
- Graph: nodes/vertices and edges
- G = (V, E, U) where, V: node attributes, E: edge attributes, U: global attributes
- Connectivity of Graph: Adjacency Matrix, a_{ij}



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What is Graph?



A simple Graph

- Graph: nodes/vertices and edges
- G = (V, E, U) where, V: node attributes, E: edge attributes, U: global attributes
- Connectivity of Graph: Adjacency Matrix, a_{ij}
- Examples: social network, citation datasets



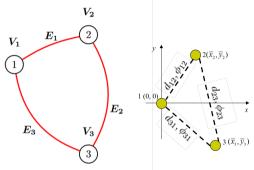
Citation Graph



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Graph Structure in WECs



3 WEC as a graph

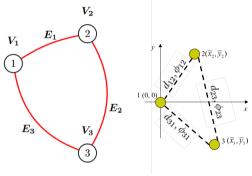
• V : buoys, E: relation/interaction between two buoys



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Graph Structure in WECs



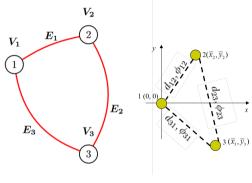
3 WEC as a graph

- V : buoys, E: relation/interaction between two buoys
- Each node has features that are independent of other buoys $V_n = \{x_i, y_i\}$
- Each edge has features that depend on i^{th} and j^{th} nodes(buoys) $E_n = \{d_{ij}, \phi_{ij}\}$
- Connectivity: interaction between buoys. No interaction, no connectivity





Graph Structure in WECs



3 WEC as a graph

- V : buoys, E: relation/interaction between two buoys
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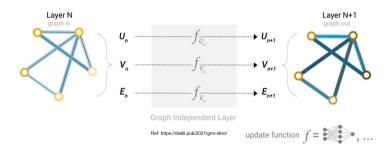
 Given different arrays can be represented with graphs, how do we predict corresponding power for a given array/graph?
 ⇒ GNN





Graph Neural Network (GNN)

• GNN: An optimizable transformation that updates various features of the graph (node, edge, global) but preserves the connectivity of the graph



Schematics of a Graph Neural Network

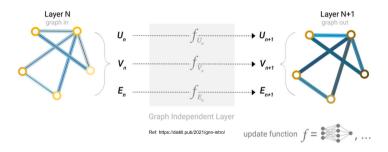


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Graph Neural Network (GNN)

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Schematics of a Graph Neural Network



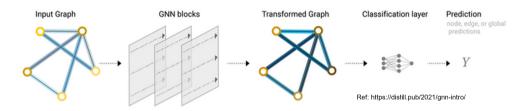
• Given updated features, how to predict?

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Predictions from GNN

Aggregate features and then use a linear layer for prediction



An end-to-end Prediction Block with a GNN Model

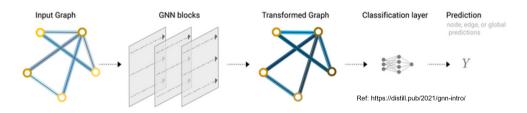


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Predictions from GNN

Aggregate features and then use a linear layer for prediction



An end-to-end Prediction Block with a GNN Model

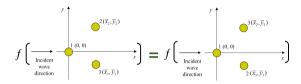
- Methods: GCN, GAT, GraphSAGE
- An invariant type GNN with randomly initaited node features used in the study, inspired by the works of Satorras et. al. (2021) and R Sato (2024)



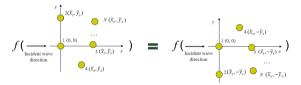
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Physics of Wave Farm



Permutation Invariance



X-Axis Reflective Invariance



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Invariant GNN with Random Node Features

Satorras et. al. (2021) have shown that the following update functions result in invariances of translation and reflection to node and edge features:

$$\mathbf{e}_{ij}^{l+1} = \phi_e(\mathbf{h}_i^l, \mathbf{h}_j^l, ||\mathbf{x}_i^l - \mathbf{x}_j^l||^2, \mathbf{e}_{ij}^l)$$

Edge Update

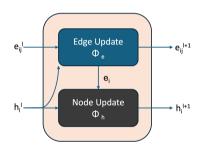
$$\mathbf{e}_i^{l+1} = \sum_{j \neq i} \mathbf{e}_{ij}^l$$

Edge Aggregation to Node

$$\mathbf{h}_i^{l+1} = \phi_h(\mathbf{h}_i^l, \mathbf{e}_i^{l+1})$$

Node Update

where, ϕ_e and ϕ_h are edge and node update functions respectively, for example: MLP



A GNN Layer

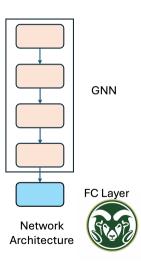


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Implementation Details

- GNN layers stacked upon each other and a fully connected layer at the end for required output size
- Edge Features: $\mathbf{e}_{ij} = [\mathbf{I}_m(d_{ij}), \ \mathbf{K}_m(d_{ij}), \ cos(\theta_{ij})] \quad m = 1, 2, ... 10$ where $\mathbf{I}_m(\cdot)$ and $\mathbf{K}_m(\cdot)$ are mth order Bessel functions of the first and the second kind
- Node Features: $\mathbf{h}_i = \text{Randomly generated from uniform distribution in } [0, 1]$
- Although randomly initialized, the network updates these features through the learning process





Implementation Details (contd...)

- Implementation is done in Python using PyTorch and PyTorch Geometric
- Edge Update Function (ϕ_e): 4 hidden layers each with 200 units and a linear layer of 20 units at the end
- Node Update Function (ϕ_h) : 3 hidden layers each with 100 units, followed by a hidden layer of 50 units and a linear layer of 10 units at the end
- After each hidden layer, ReLU is applied as non-linear layer
- MSE is used as loss function and model trained for 5000 epochs. Train:Val:Test Split = 6400:800:800
- Learning Rate Scheduler and Early Stopping which are standard practices in ML are also implemented
- For learning rate scheduler, PyTorch's 'ReduceLRonPlateau' is used, which reduces learning rate up to a certain limit if the validation loss does not decrease within a threshold for some epochs

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Results

Training and Validation Loss

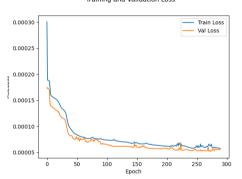


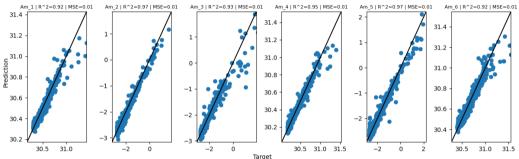
Figure: Loss over Epochs for Added Mass Coefficient Training



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Prediction of Added Mass for $\omega = 0.3$

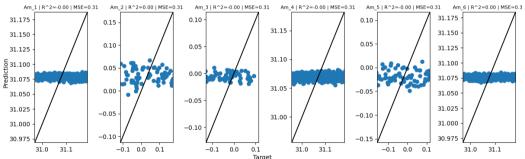




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Prediction of Added Mass for $\omega = 1.4$

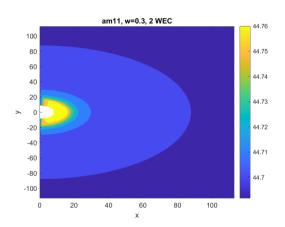


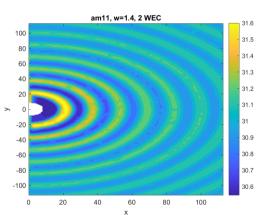


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Variation of Added Mass Coefficient







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Conclusion

- An invariant Graph Neural Network with randomly initialized node features was designed to predict hydrodynamic coefficients of wave energy converter arrays
- For lower frequencies of incoming wave, the model predictions are good $(R^2 > 0.90)$ but poor performance for higher frequencies
- The underlying variation of coefficients for higher frequencies is too difficult to capture for the given model architecture



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- For lower frequencies of incoming wave, the model predictions are good $(R^2 > 0.90)$ but poor performance for higher frequencies
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Future Work:

- Analyse the case for higher frequencies and get good predictions
- Work on other hydrodynamic coefficients
- Model power generation after getting good results on coefficients



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